

Topology Notes

David Wright

January 21, 2021

Contents

1 Preliminaries	1
2 Metrics and Norms	2

These notes are from my spring 2021 Introduction to Topology course. This course was taught by Dr. Gary Richardson at UCF out of C. Wayne Patty's *Foundations of Topology*, 2nd ed.

1 Preliminaries

Definition 1.0.1 (De Morgan's Laws). De Morgan's Laws give us relations between unions, intersections, and complements of sets.

Let X be a set and $A_j \subset X, j \in J$ (J is an **index set**). Then,

$$1. \left(\bigcup_{j \in J} A_j \right)^C = \bigcap_{j \in J} A_j^C$$

$$2. \left(\bigcap_{j \in J} A_j \right)^C = \bigcup_{j \in J} A_j^C$$

Lemma. Let $f : x \rightarrow y, A_j \subseteq X, A \subseteq X, B_j \subseteq Y$. Then,

$$1. f\left(\bigcup_{j \in J} A_j\right) = \bigcup_{j \in J} f(A_j)$$

$$2. f\left(\bigcap_{j \in J} A_j\right) \subseteq \bigcap_{j \in J} f(A_j)$$

$$3. f^{-1}\left(\bigcup_{j \in J} B_j\right) = \bigcup_{j \in J} f^{-1}(B_j)$$

$$4. f^{-1}\left(\bigcap_{j \in J} B_j\right) = \bigcap_{j \in J} f^{-1}(B_j)$$

$$5. f^{-1}(B^C) = (f^{-1}(B))^C$$

$$6. f(A^C) \subseteq (f(A))^C \text{ no nice connection}$$

2 Metrics and Norms

Definition 2.0.1 (Norm). A norm " $\|\cdot\|$ " is a map

$$\|\cdot\| \rightarrow [0, \infty]$$

Given a vector space V over \mathbb{R} ; $x \in V$ and $\alpha \in \mathbb{R}$, a norm has the following properties:

1. $\|x\| = 0 \iff x = 0$
2. $\|\alpha x\| = |\alpha|\|x\|$
3. $\|x + y\| \leq \|x\| + \|y\|$

Lemma. Let V be a vector space with norm $\|\cdot\|$. Define $d = \|x - y\|$. Then d is a metric on V .

Definition 2.0.2 (Metric). Given a set X and $x \in X$, $d : x \times x \rightarrow (0, \infty)$ is a metric if:

1. $d(x, y) = 0 \iff x = y$
2. $d(x, y) = d(y, x)$
3. $d(x, y) \leq d(x, z) + d(z, y) \forall x, y, z$

Ex. 2.0.1 (Norm in \mathbb{R}^n).

$$\|x \in \mathbb{R}^n\| = \left(\sum_{i=1}^n x_i^2 \right)^{1/2}$$

Ex. 2.0.2 (Euclidean Metric in \mathbb{R}^n). $d(x, y) = \|x - y\| = \left(\sum_{i=1}^n (x_i - y_i)^2 \right)^{1/2}$

Ex. 2.0.3 (l_2 Metric). Given

$$l_2(\mathbb{R}) = \left\{ (x_i) \mid x_i \in \mathbb{R}; \sum_{i=1}^{\infty} x_i^2 < \infty \right\}$$

Define $\|x\| = \left(\sum_{i=1}^{\infty} x_i^2 \right)^{1/2}$. Then the metric is

$$d(x, y) = \|x - y\| = \left(\sum_{i=1}^{\infty} (x_i - y_i)^2 \right)^{1/2}$$

Ex. 2.0.4 (l_1 "Taxi Cab" Metric). Given

$$l_1(\mathbb{R}) = \left\{ (x_i) \mid x_i \in \mathbb{R}; \sum_{i=1}^{\infty} |x_i| < \infty \right\}$$

Define $\|x\| = \sum_{i=1}^{\infty} |x_i|$. Then the metric is

$$\rho(x, y) = \|x - y\| = \sum_{i=1}^{\infty} |x_i - y_i|$$

Ex. 2.0.5 (Metric on Continuous Functions). On an interval $[a, b]$:

Given

$$\{f \mid f : [a, b] \rightarrow \mathbb{R}; f \text{ continuous}\}$$

Define $\|f\| = \int_a^b |f(x)| dx$. Then the metric is

$$d(f, g) = \|f - g\| = \int_a^b |f(x) - g(x)| dx$$

Ex. 2.0.6 (Square Metric).

$$\sigma(x, y) = \|x - y\| = \max \{|x_i - y_i| \mid i \in [1, n]\}$$

Ex. 2.0.7 (Discrete Metric).

$$d(x, y) = \begin{cases} 0, & x = y \\ 1, & x \neq y \end{cases} \quad (1)$$

Definition 2.0.3 (Open Ball). Given a point x , and open ball around it is denoted by

$$B(x, \delta) = \{y \in X \mid d(x, y) < \delta; \delta > 0; x \in X\}$$

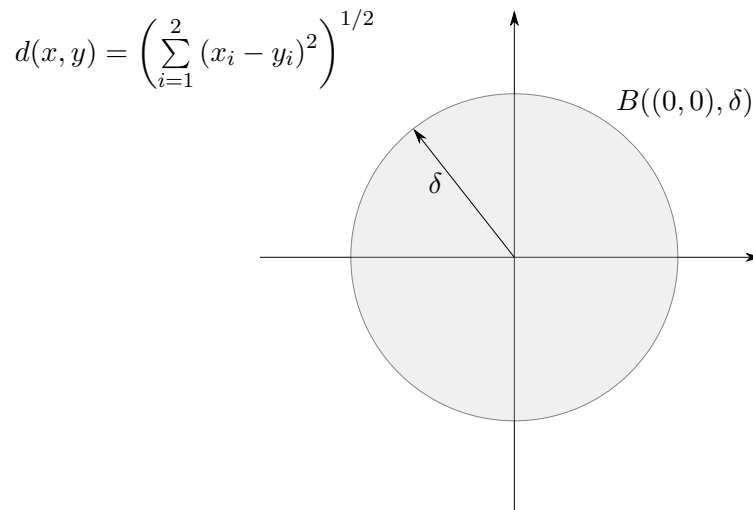


Figure 1: An open ball with the Euclidean Metric

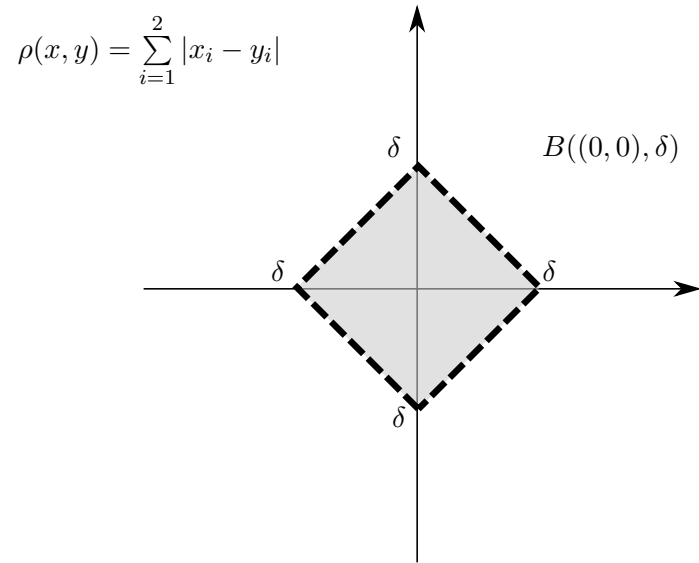


Figure 2: An open ball with the l_1 Metric

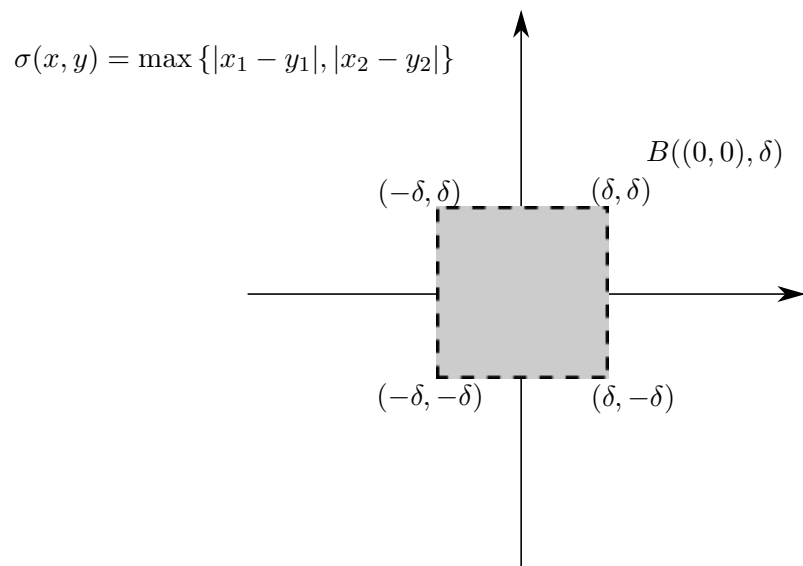


Figure 3: An open ball with the Square Metric